

MUNEER KALAMKULATH

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OBJECTIVE

To contribute in the development of fields, in electronics that help in creating a smarter and safer tomorrow by working in a company that focus on a creative and healthy environment, which will give me an opportunity to improve my technical skills along with achieving organization goals with my knowledge base.



EDUCATION

Bachelor of Engineering in Electronics & Communication | 2017

INSTITUTE: P.A. COLLEGE OF ENGINEERING, MANGALORE -
KARNATAKA, INDIA

UNIVERSITY: VISVESWARAYA TECHNOLOGICAL UNIVERSITY,
KARNATAKA, INDIA

Higher Secondary Education (XII)| 2011

INSTITUTE: GOVT. HIGHER SECONDARY SCHOOL, CHORODE

UNIVERSITY: STATE BOARD OF SECONDARY EDUCATION, KERALA

Secondary Education (X)| 2009

INSTITUTE: GOVT. HIGHER SECONDARY SCHOOL, CHORODE

UNIVERSITY: KERALA STATE BOARD



EXPERIENCE

WEIGH CONTROL SYSTEMS, BANGALORE, KARNATAKA, INDIA (July 2017- Dec 2018)

1. Worked as a **SERVICE ENGINEER.**

- Responsible for servicing and maintaining the industrial machines like Oil & Polymer batching system, Weigh bridge, Tank weighing system, Bag & Jumbo bag filling machine, Tin and Barrel filling machine, Oil vending machine etc..

2. After 1 year, moved to software department as a **PLC & HMI Programmer.**

- Responsible for creating software in PLC ladder language, Handling PLC based projects, HMI programming, Wiring, Testing software and Hardware up to final stage and installation of PLC based machine.



CERTIFICATION

- **P.G Diploma in Automation and Control Engineering**
Institution: Technologies, Bangalore
- **Automatic Transmission & Computerised Vehicle Diagnosing**
Institution: Indian Institute of Automatic Transmission, Calicut



PROJECT

Cobot (A Ground & Aerial Obstacle Avoiding Vehicle) | Completed

Description: This Bot is a combination of ground and aerial vehicle having stealth ability at hard to reach places, It is designed especially for military purpose. It can maneuver on ground, detect obstacles and can overcome them by activating the quad copter attached to it. The purpose of this unified model is to complete a task at a location where either a ground bot or drone being in standalone mode cannot achieve, maintaining its stealth feature which is highly recommended in war prone regions.



SKILLS

- Programmable Logic Controllers (Advanced)
- Human Machine Interfacing (Advanced)
- Variable Frequency Drives (Advanced)
- Embedded Systems (Intermediate)
- Supervisory Control & Data Acquisition Systems (Advanced)
- HTML (Beginner)
- C programming (Beginner)



ACHIEVEMENTS

- Conducted Seminar on the topic **A Driver Support System to Prevent Traffic Accidents Caused by Optical Illusions**
- Attended a training program on Bosch Engine management system& vehicle Diagnosis using KTS 570 with Bosch ESI [tronic] software



PERSONEL DETAILS

- Language : English, Hindi, Malayalam
- Date of Birth: 06th June 1993
- Passport No :L8613129
- Gender: Male
- Nationality: Indian
- Visa Status : Work-Business Visa



DECLARATION

I hereby declare that the above information is true to best of my knowledge.

(**MUNEER KALAMKULATH**)

Place: QATAR